Novel categories are distinct from "Not"-categories

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Abstract

The categorization literature often considers two types of categories as equivalent: (a) standard categories and (b) negation categories. For example, category learning studies typically conflate learning categories A and B with learning categories A and NOT A. This study represents the first attempt at delineating these two separate types of generated categories. We specifically test for differences in the distributional structure of generated categories, demonstrating that categories identified as *not* what was known are larger and wider-spread compared to categories that were identified with a specific label. We also observe consistency in distributional structure across multiple generated categories, replicating and extending previous findings. These results are discussed in the context of providing a foundation for future modeling work.

Keywords: categorization; category generation; contrast; category learning;

Introduction

People are remarkable in their capacity to innovate new and different ideas. Is creating a new idea the same as creating a different idea? Consider a restaurant that serves one meal per night. Their chef cooked red curry last night and wants to create and cook a new dish tonight. Is that the same as wanting to create and cook a new dish that is *not* red curry? While the former is identified as its own category, the latter is identified in relation to a known category.

While categorization researchers have primarily focused their effort on classification (associating an exemplar with a category given its features), and inference (predicting exemplar features given its category), work on category generation – predicting all exemplar features for a novel category – is relatively scarce. This is surprising because category generation is not an uncommon phenomenon – people are constantly challenged to generate novel categories, such as a new meal plan for the week, a new music playlist for an upcoming road trip, or a new exercise regimen to stay healthy.

Recent category generation work has established a few key findings. Earlier studies have shown that generated categories tend to share distributional statistics with learned categories (Jern & Kemp, 2013; Thomas, 1998; Ward, 1994). More recently, Austerweil, Conaway, Liew, and Kurtz (in preparation) and Conaway and Austerweil (2017) have found that category contrast is an important factor in category generation and learning – computational models sensitive to the differences between categories were a better fit to generated

categories than models which did not take categories contrast into account.

Although previous work has established a few key findings, the basic phenomena and processes involved in category generation are still not well understood. In this article, we examine whether given a known category in a domain, generating a new category is different from generating a category that is not the learned category. If the only category is A, most formal accounts of categorization would consider generating a new category B as equivalent to generating not A. In order to better understand the nature of generated categories, it is necessary to distinguish between these two possible types of generated categories: one driven by its own identity – an *independently identified category*, and another driven by a motivation to be not what is known – a *category-by-negation*.

Current models of category generation do not explicitly make this distinction. One of the first computational models of category generation, Jern and Kemp (2013)'s hierarchical sampling model, is a Bayesian model that reproduces distributionally similar categories by assuming that the covariance matrix of features of exemplars from generated categories is generated by the same prior that generated the covariance matrix of the known categories. An alternative proposed model, PACKER (Conaway & Austerweil, 2017), is an extension of the classic Generalized Context Model (GCM; Nosofsky, 1984, 1986). It explicitly incorporates contrast into the similarity function by including a penalty for being similar to exemplars from a known category. A contrast parameter allows candidate categories that are more different from the known category to be weighted more heavily than candidate categories similar to the known category. Both models are flexible enough to describe how generated categories can be distributionally similar (or different) from an experimenter-defined category. However, they do not distinguish between generating an independently identified category and a category-bynegation because there is no mechanism to account for these different identities.

This issue also extends to the methodology applied in category generation (as well as most categorization studies.) In Ward (1994), participants were told to generate aliens that belonged to a different species from a prior group of aliens, without applying any specific label to this new group of aliens. Similarly, Jern and Kemp (2013) instructed participants to generate a new, different type of crystal after having

observed two different types of crystals. In contrast, Conaway and Austerweil (2017) prompted participants to generate exemplars from a novel "Beta" category, while avoiding an explicit instruction for participants to create something "different". In each of these studies there appears to be an implicit assumption that generating an independently identified category is equivalent to generating a category-by-negation.

In this paper, we challenge this null assumption by positing that the explicit association of categories-by-negation to its known counterpart (i.e., the explicit identification of the to-be-generated category as not a known category) should result in the observer taking advantage of the entire area of the feature space not occupied by the known category. In contrast, observers generating independently identified categories should be less focused on the unoccupied feature space and instead construct their categories based on the structure of known categories. From this we can predict that categoriesby-negation should occupy larger areas of the feature space compared to independently identified categories. In addition, the similarity in distributional statistics should extend not only from the learned category to the first independently identified category to be generated (as previous studies have found), but also between subsequent independently identified categories. We test these predictions by adapting and extending a category generation experiment by Conaway and Austerweil (2017) and explore the implications of its results.

Experiment

Our current experiment closely mirrors the the experimental design of Conaway and Austerweil (2017), where participants are first trained on a category named 'Alpha' before being tasked to generate exemplars from a new category. While Conaway and Austerweil (2017) were primarily interested in the measuring the location of generated categories relative to learned categories, our current investigation focuses on analyzing the differences in distributional statistics across different generated categories. Consequently, in addition to varying the shape and location of the Alpha category (i.e., across different Alpha conditions where the position of the Alpha exemplars are systematically varied) in three distinct ways, we include an additional independent variable comprising three different generation conditions: a Not-Alpha condition, where participants generate a new category that is not the learned Alpha category; a Beta-Only condition, where participants generate a new category named 'Beta'; and a Betaand-Gamma condition, where participants generate a category 'Beta' as well as a category 'Gamma'. The resulting 3-by-3 design is applied in a between-subjects fashion – participants can be in only one of the nine unique conditions.

The main advantage of adapting the experiment by Conaway and Austerweil (2017) is that the simplicity of their stimuli allow for a straightforward test of the distributional similarities across known and generated categories. In addition, the variety of Alpha categories used (i.e., the different shapes of the Alpha categories) also allows us to observe the

effect of generated category identity across multiple scenarios

In line with our earlier predictions, we expect that the Not-Alpha conditions on average generate categories that are larger in area and more widely dispersed than categories from the Beta-Only as well as Beta-and-Gamma conditions. In addition, we predict that within the Beta-and-Gamma conditions, the generated Beta and generated Gamma categories should be distributionally similar.

Method

Participants and materials We recruited 240 participants through Amazon Mechanical Turk and randomly assigned them to one of the nine unique conditions. Sample sizes of each condition are presented in Table 1.

Stimuli were squares that varied along two dimensions: color (grayscale 9.8% - 90.2%) and size (3.0 - 5.8cm on each side). The assignment of perceptual features (color, size) to axes of the domain space (x, y), as well as the direction of variation along each axis (e.g., increasing or decreasing size) was counterbalanced across participants. Feature values were evenly-spaced on a 50-by-50 grid, giving a near-continuous space from which exemplars can be generated. An example of the feature space is presented in Figure 1a.

The three Alpha conditions are Cluster, Row, and Diagonal. In the Cluster condition, Alpha exemplars occupy a small area towards one corner of the feature space. In the Row condition, the exemplars are nearly equal along one feature, while equally spread out along the other feature. The Diagonal condition has Alpha exemplars equally spaced along the diagonal of the feature space in a similar fashion to the diagonal conditions of Jern and Kemp (2013). In order to ensure that exemplars are not completely identical along any one feature, exemplar feature values are slightly jittered. The exact same amount of jitter is applied to all Alpha exemplars within a given Alpha condition. The locations of these different Alpha categories in the feature space are presented in Figures 1b to 1d.

Procedure In the first phase of the experiment (Figure 2), participants learned the Alpha category exemplars by observing a unique exemplar on each trial. This was repeated over a total of three blocks (four trials per block – one corresponding to each unique exemplar,) with the order of exemplar presentation randomized within each block. Prior to the presentation of each exemplar, a fixation cross was shown for 1000 ms. Participants were allowed to spend as much time as they wanted on each trial and were also shown the full range of possible feature values prior to training.

The next phase comprised a series of generation trials (Figure 3). Depending on their generation condition, participants generated either eight exemplars from a category that was 'Not-Alpha' (Not-Alpha generation condition), eight exemplars from a category called 'Beta' (Beta-Only generation condition), or four exemplars from a category 'Beta' *and* four exemplars from a third category 'Gamma' (Beta-and-Gamma

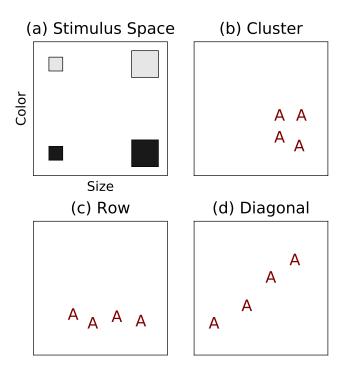


Figure 1: (a) Example of stimuli located at the corners of the feature space. (b-d) Locations of Alpha category exemplars for each Alpha condition.

generation condition). More specifically, participants in the Not-Alpha generation condition were asked to produce "what [they] think is likely to NOT be in the Alpha category", while participants in the other conditions were asked to produce "what [they] think is likely to be in the Beta [or Gamma] category". Exemplars were generated on each trial using two on-screen sliding scales, with each scale controlling the individual features (color and size) of the generated exemplar. Feature values could take any one of 50 evenly-spaced values between the specified boundaries. Previously generated exemplars were not allowed to be generated a second time. Participants were shown an on-screen preview of their exemplar on each trial as they interacted with the sliders, but could not see previously generated exemplars or exemplars from the Alpha category.

Table 1: Sample sizes for each condition.

Generation Condition	Cluster	Row	Diagonal
Not-Alpha	26	28	25
Only Beta	30	27	25
Beta-and-Gamma	26	27	26

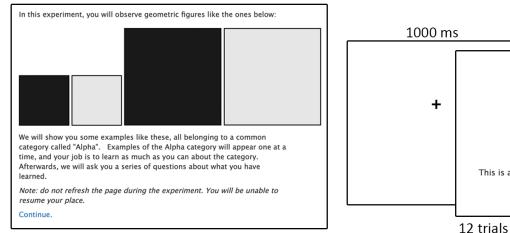
Analyses We analyze our data in two stages. First, to provide a coarse overview of the distribution of different patterns of generated categories, we classify the generated categories

into six different profiles: Positives, where the correlation between the dimensions is more than r; Negatives, where the correlation between the dimensions is less than -r; Rows, where the range of values across the x dimension is at least dtimes more than the range across the y dimension; Columns, where the range of y dimension values is at least d times more than the range of x dimension values; Clusters, where the ranges across both dimensions are less than a; and Dispersed, where the ranges across both dimensions are more than a. Next, we compare the generated categories on four key distributional measures: ranges of each feature, the feature correlations, and the area enclosed by the generated exemplars in the feature space (i.e., their convex hull). Differences along each of these statistics are performed using Bayesian t-tests (Rouder, Speckman, Sun, Morey, & Iverson, 2009), yielding Bayes factors (BF_{01}) which indicate evidence for the null hypothesis when $BF_{01} > 1$, with larger values indicating greater evidence for the null hypothesis. $BF_{01} < 1$ indicates evidence for the alternative hypothesis. Interpretations of the sizes of Bayes factors are guided by Jeffreys (1961).

Results

We took a subset of the data and tuned each of the profiling parameters such that the profiles of this subset were adequately captured. Subsequently, we applied this profiling scheme to the entire dataset. Overall, we found that setting r=.7, a=.25, and d=5 was useful in capturing the different profiles of generated categories. The results were robust to moderate variations in the profiling parameters (e.g., setting .5 < r < .9, .1 < a < .4, and d>1 returned very similar results.) A representative sample of each profile is shown in Figure 4 and the frequency plot of the different profiles is presented in Figure 5.

The most striking patterns to note here are the high frequencies of Row category profiles from participants in the Row conditions, and the high frequencies of Dispersed category profiles from participants in the Not-Alpha conditions. The former indicates that the distributional similarities between learned and generated categories are especially strong in the Row conditions, while the latter provides preliminary evidence that generated categories from the Not-Alpha conditions tends to be more widely dispersed. Also noteworthy are the low counts of both Positive and Negative category profiles across the whole data set – in contrast to the Row conditions, this indicates low similarity in distributional structure between the learned and generated categories for the Diagonal condition.



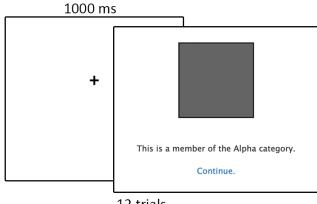
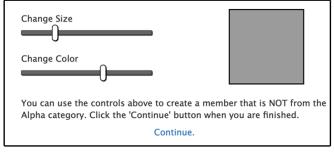


Figure 2: Instructions and trials observed by each participant during the category learning phase. The instructions screen is shown once, followed by 12 presentations of Alpha exemplars (4 exemplars across 3 blocks.)

There is another category of geometric figures that are NOT from the Alpha category. Instead of showing you examples, we would like to know what you think is likely to NOT be in Alpha category.

You will now be given the chance to create examples of any size or color in order to show what you expect would NOT be in the Alpha category. You will be asked to produce 8 examples - they can be quite similar or quite different to each other, depending on what you think makes the most sense for this category. Each example needs to be unique, but the computer will let you know if you accidentally create a repeat.

Continue.



8 trials

Figure 3: Instructions and trials during the generation phase, observed by a participant in the Not-Alpha condition. Participants in the Beta-Only and Beta-Gamma conditions experienced similar trials, with the exception that those in the Beta-Gamma condition were asked to generate 4 Beta exemplars then 4 Gamma exemplars.

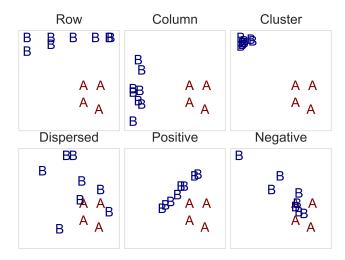


Figure 4: Representative samples of the six different category generation profiles.

Focusing on the distributional statistics, when broken down by the Alpha conditions (Figure 6), we found that the Cluster conditions tended to have categories with a smaller range of both features, and with correspondingly small sizes. The Row conditions produced categories that are high on the x dimension but not the y dimension. These observations indicate that the distributional statistics were carried over from the known category to the generated category in these two Alpha conditions. However, the Diagonal conditions did not have similar distributional statistics observed – instead of a positive correlation, the Diagonal conditions tended to produce large, dispersed categories. Austerweil et al. (in preparation) also observed a similar effect (although they found more evidence for a negative correlation). Overall, in alignment with previous research, at least two out of the three Alpha conditions in our experiment generated categories that share distributional statistics as the known category.

More interestingly, when the data is broken down by the generation conditions (Figure 7), we found that compared to the Not-Alpha conditions, there is moderate evidence showing Beta-Only conditions with a lower y dimension range $(t(162) = 3.00, BF_{01} = 0.16)$ and moderate to strong evidence that their generated categories are smaller in area (t(162) =3.16, $BF_{01} = 0.10$). There is moderate evidence that the Not-Alpha and Beta conditions share equal range of x dimension values ($t(162) = 1.33, BF_{01} = 4.82$). With Beta-and-Gamma conditions, we find greater evidence for smaller and tighter categories compared to the Not-Alpha conditions. Specifically, there is very strong evidence that both Beta and Gamma categories from the Beta-and-Gamma condition are smaller in both x $(t(156) = 4.83, BF_{01} = 2.55 \times 10^{-4}; t(156) = 4.21,$ $BF_{01} = 2.94 \times 10^{-3}$, respectively) and y (t(156) = 4.57), $BF_{01} = 7.40 \times 10^{-4}$; t(156) = 7.56, $BF_{01} = 4.30 \times 10^{-10}$, respectively) ranges compared to the Not-Alpha conditions. Similarly, there is very strong evidence that both categories in the Beta-and-Gamma conditions are smaller in area than the Not-Alpha conditions $(t(156) = 5.70, BF_{01} = 5.41 \times 10^{-6}; t(156) = 7.69, BF_{01} = 2.07 \times 10^{-10},$ respectively). Overall, when comparing the Not-Alpha conditions to categories from other generation conditions, we consistently find moderate to very strong evidence that Not-Alpha categories are more widely dispersed (in their range values) and also larger (in their area), with the only exception being the comparison of x dimension ranges between the Not-Alpha and Beta-Only conditions.

When comparing the distributions of the Beta and Gamma categories generated within the Beta-and-Gamma conditions, we find an overall weak-to-moderate evidence for equal distributional statistics. Specifically, there was moderate evidence for equal x dimension ranges $(t(150) = 0.56, BF_{01} = 9.47)$ and weak evidence for both feature correlations and area size $(t(150) = 1.85, BF_{01} = 2.10; t(150) = 1.77, BF_{01} = 2.40$, respectively). When measured on their y dimension ranges, we found weak evidence for lower values from Gamma categories compared to the Beta categories $(t(150) = 2.47, BF_{01} = 0.59)$.

Discussion

At first glance, it seems reasonable to assume that generating a new category Y after learning category X is the same as generating a new category Not-X. An independently identified category should already be a category-by-negation (in that an independently identified category is not what was previously known.) Further, if the categories are already identified by arbitrary labels, then it may be easy to assume that identifying the negation of a known category cannot add any additional information in category generation.

Our results have indicated otherwise. Specifically, when tasked to produce categories-by-negation, participants tended to generate wider and larger new categories compared to when tasked with producing independently identified categories. To our knowledge, this paper represents the first piece of evidence distinguishing these separate types of categories.

Aside from demonstrating a new effect, this study has continued to show the robustness of the distributional similarities between learned and generated categories. In this sense, the results from the different Alpha conditions are similar to those observed in Austerweil et al. (in preparation). The generated categories from the Cluster condition tend to possess lower x and y ranges, with a correspondingly smaller area, and the generated categories from the Row condition tend to adopt Row-type profiles. There is also similar lack of categories with positively correlated features from the Diagonal condition.

However, one notable difference is that while Austerweil et al. (in preparation) found evidence of negatively-correlated generated categories in their XOR condition, we found no evidence of negatively-correlated generated categories in our comparable Diagonal condition. Austerweil et al. (in preparation) explained that the presence of negatively-correlated

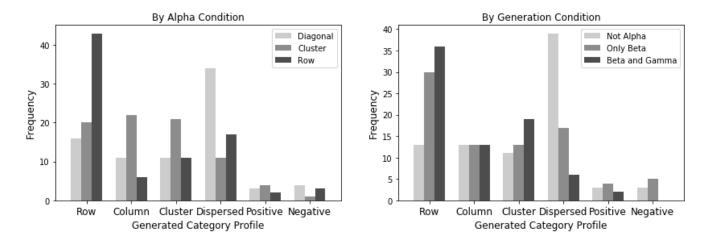


Figure 5: Frequencies of category generation profiles broken down by Alpha condition (left plot) and generation condition (right plot).

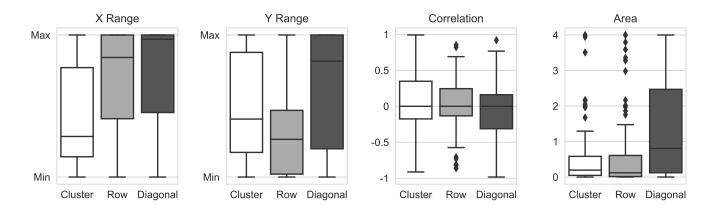


Figure 6: Box-plots of the distributional statistics from the generated categories. Boxes depict the median and quartiles of each Alpha condition, with whiskers placed at 1.5 inter-quartile range. All points outside this region are marked individually.

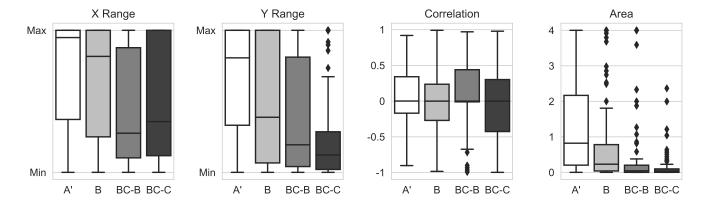


Figure 7: Box-plots of the distributional statistics from the generated categories. Boxes depict the median and quartiles of each generation condition, with the Not-A condition denoted by A' and the Beta-Only condition denoted by B. Data from the Beta-and-Gamma conditions are separated into the Beta groups (denoted BC-B) and the Gamma groups (denoted BC-C) generated in that condition. Whiskers are placed at 1.5 inter-quartile range. All points outside this region are marked individually.

features in this condition was indicative of the effect of category contrast – that is, categories with negatively correlated features are generated because they are particularly different to categories with positively correlated features. It is possible that due to the reduced strength of the positive correlation in our study compared to Austerweil et al. (in preparation) (because of the addition of noise to the feature values), participants were no longer as sensitive to the negative correlations in the experimenter-defined category and therefore started to produce uncorrelated but widely dispersed categories.

Beyond replicating previous studies, the current study has demonstrated that the consistency in distributional statistics can persist beyond the first generated category. However, evidence showing this was ultimately weak. One possible reason for this is the relatively small feature space employed in the tasks. The generation of a second novel category is necessarily more constrained in the feature space than the generation of the first novel category, possibly contributing to differences in distributional structure. By exploring stimuli features with less defined boundaries (e.g., orientation), we may expect to see greater consistency in distributional structure over multiple generated categories.

Although we have observed participants generating multiple independently identified categories, we do not want to imply that categories-by-negation can only happen once. It would be worth investigating how participants might proceed to generate additional categories-by-negation (e.g., by asking observers to generate a category that is Not-Alpha and Not Beta). Packing Theory (Hidaka & Smith, 2011) – a hypothesis that suggests categories can be neatly 'packed' into the feature space - may indicate that successive categories-bynegation are generated in a fashion that preferentially occupies spaces between observed categories. Further, although none of the current models of category generation can directly account for the effects observed in this study, they may be useful components in a larger category generation framework. For instance, future work may consider implementing the hierarchical sampling model from Jern and Kemp (2013) in a framework of overhypotheses (Kemp, Perfors, & Tenenbaum, 2007), where a prior can be placed over a category identity space, allowing models to behave differently under different regions of generated category identity.

Ultimately, the nature of newly generated categories appears to vary depending on the identity they were associated with. The extent to which they may differ, and the mechanisms driving these differences represent fascinating areas for future research.

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